

Mechanical Properties of Agglomerates Produced by the Mechanical Vibration of Cohesive Powders[†]

Hamid Salehi Kahrizsangi, Diego Barletta and Massimo Poletto*

¹ Department of Industrial Engineering, University of Salerno, Italy

Abstract

The process of granule formation from aggregative cohesive powders under the action of mechanical vibration is studied. Vibration frequency and acceleration levels were set independently in the experiments. The process of agglomerate formation is examined by measuring the size distributions of the agglomerates and their resistance under uniaxial compression. The results indicate the formation of wide particle size distributions and hard and compact agglomerates. The experimental results and the interpretation of data suggest that, in order to produce agglomerates by mechanical vibration, powders should have flow functions with a flow factor value smaller than 3. In agreement with the theoretical framework proposed, agglomerate consolidation pressures and deformation at breakage seem to be almost independent of the agglomerate diameter and the vibration conditions.

Keywords: cohesive powders, mechanical vibration agglomerates, compression test

1. Introduction

Powder granulation is used in many different industrial applications such as the production of pesticides, fertilizers and ceramics. The general purpose is to improve the handling and the storage behavior of these solid materials. On the one hand, with fine and cohesive powders, mechanical vibrations can be used to produce stable agglomerates (Kua N. et al., 2014; Mawatari Y. et al., 2007). On the other hand, the self-agglomeration of cohesive powders may happen in processes involving mechanical vibrations, leading to undesired problems. Among these, we mention solids segregation in processes involving powder flow and also gas-solids segregation in industrial applications which require an intimate gas-solids contact. The aggregative behavior of fine cohesive powders under the action of vibrations was described by Barletta D. and Poletto M. (2012) following the analysis introduced previously (Barletta D. et al., 2007). Nano-powders also produce self-aggregation phenomena in vibrated beds (Van Ommen J.R. et al., 2012). Mechanical vibrations have also been applied together with powder drying processes to control and promote powder agglomeration (Cruz M.A.A. et al., 2005). The objective of this paper, however, will be the agglomeration of cohesive powders due to compaction

in vibrated beds without the use of a fluidizing gas or at least under application of a minimum gas rate with the purpose of system conditioning, but not the ability to sustain the bed.

One of the most significant characteristics of a granulation process is the granules' mechanical resistance. In fact, the produced granules should be able to resist the external forces during storage and transportation in order to avoid dust formation and changes to the granules' size distribution. A recent study on the resistance of agglomerates under the action of compression and their mechanical behavior was given by Antonyuk S. et al. (2005). They provided a significant insight into the rupture mechanism and into the mechanical response of agglomerates for elastic, elastic-plastic and plastic agglomerate deformation regimes. The resistance of agglomerates in dynamic conditions was studied by Antonyuk S. et al. (2006).

In this paper, the process of granule formation from aggregative cohesive powders under the action of mechanical vibration is studied. The equipment used allows the vibration frequency and acceleration levels to be set independently. The process of agglomerate formation is examined by measuring the agglomerate's size distributions and also by the agglomerate's resistance under uniaxial compression.

2. Experimental

2.1 Apparatus

The apparatus used is described by Barletta D. et al.

[†] Received 16 May 2015; Accepted 6 July 2015

J-STAGE Advance published online 21 August 2015

¹ Via Giovanni Paolo II, 132, 84084 Fisciano (SA), Italy

* Corresponding author: Massimo Poletto;

E-mail: mpoletto@unisa.it

TEL: +39-089-96-4132 FAX: +39-089-96-8781

(2013). A sketch of the apparatus, a vibrated fluidization column, is shown in **Fig. 1**. The fluidization column was made of Perspex with an 85-mm ID and a height of 400 mm (1). At the bottom, the air was distributed by a 10-mm thick porous plate of sintered brass particles. The porous plate was clamped in the flange connecting the wind box and the fluidization column. In the column flange, a pressure port was connected to a U-tube manometer (6) filled with water. Desiccated air from the laboratory line was fed to the wind box by a thermal mass flow controller (Tylan FC2900V) with a maximum flow rate of $5 \cdot 10^{-5} \text{ Nm}^3 \text{ s}^{-1}$ (4). The column was fixed to the vibrating plane of the actuator by means of a rigid steel and aluminum structure (3). The actuator (2) was an electric inductance vibrator (V100 Gearing and Watson, USA) that was able to produce a sinusoidal vertical movement in the range between 2 and 6500 Hz with displacement amplitudes of up to 12.7 mm, exerting a maximum force of 26.7 kN. The vibrator amplifier was connected to a vibration controller Sc-121 (Labworks inc., USA) (7). The controller measured the effective vibrations by means of a piezoelectric accelerometer (8636B60M05 Kistler, USA) (5) fixed on the metal structure supporting the fluidization column. The system was able to control vibrations by fixing, within the operating range, any of the two possible pairs of vibration parameters, *i.e.* acceleration, amplitude

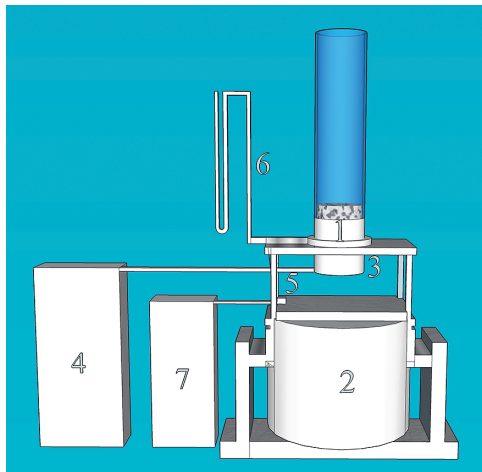


Fig. 1 Schematic of a mechanically vibrated bed. Legend: 1. fluidization column; 2. electro-dynamic vibrator; 3. metallic frame; 4. mass flow controller and air feed unit; 5. accelerometer; 6. water manometer; 7. vibration control block.

or frequency. In fact, the maximum acceleration, a , is related to the oscillation amplitude, A , and the oscillation frequency, f , or the pulsation value, ω by means of the following relationship:

$$a = A\omega^2 = A(2\pi f)^2 \quad (1)$$

In our experiments, we chose to define the vibration acceleration and the frequency.

2.2 Materials

Two different powders were used in the experiments, a calcium carbonate (CaCO_3) powder and a titanium dioxide (TiO_2) powder. The properties of these two powders are reported in **Table 1**. The rheological properties were measured with a Schulze ring shear tester (Schulze D., 1994). The flow functions (unconfined yield strength as a function of the major principal stress) at high consolidation values, namely between 10 kPa and 170 kPa, were measured with a uniaxial testing procedure carried out on an Instron tester (Series 5860) equipped with a 1-kN load cell. The mold was a steel cylinder made of two detachable halves as described by Parrella L. et al. (2008). It allowed the production of cylindrical samples of compacted powder of 50 mm in diameter and about the same height. In order to compensate for wall friction in the consolidation phase, a Janssen (Janssen H.A., 1895) correction was used to determine the vertical consolidation stress during the uniaxial compression tests

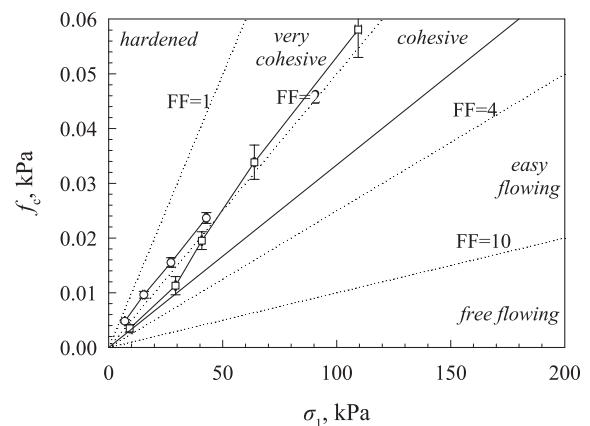


Fig. 2 Flow functions of calcium carbonate (\circ) and of titanium dioxide (\square) measured with a uniaxial testing procedure.

Table 1 Material properties

Material	d_p μm	ρ_p kg m^{-3}	σ_1 Pa	f_c Pa	ρ_b kg m^{-3}	ϕ deg	ϕ_e deg	ϕ_w deg	S_c^*/d_a Eqn. (15)
CaCO_3	4.1	2540	471	410	350	35	50	30	0.039
TiO_2	0.2	4500	345	300	785	40	50	39	0.019

$$\sigma = \sigma_0 \exp\left(-\frac{4\mu_w Kz}{D}\right) \quad (2)$$

where D is the mold diameter, z is the final sample height after consolidation, σ_0 is the applied stress on the sample surface, $\mu_w = \tan \phi_w$ is the mold wall friction, ϕ_w is the wall friction angle, K is the vertical to horizontal stress ratio that, for lack of a better evaluation (Barletta D. and Poletto M., 2013), it is calculated as suggested by Kwade A. et al. (1994):

$$K = 1.2(1 - \sin \phi_e) \quad (3)$$

where ϕ_e is the effective angle of internal friction. The wall friction tests of the powders were measured by a Brookfield Powder Flow tester by using a stainless steel coupon.

2.3 Procedure

Beds of cohesive calcium carbonate and titanium dioxide powders were vibrated vertically at frequencies of 25 or 50 Hz and at acceleration levels, a/g , of 6 or 9. A desiccated air flow was used to keep the powder humidity constant during the experiments. The experimental conditions for both materials are reported in **Table 2**. For calcium carbonate, if we assume test C3 as a reference case, then the other test conditions change for one or maximum two variables. Namely, in Test C1, half of the process time is considered; in Test C2, the frequency is doubled and the processing time is tripled; in test C4, the acceleration is reduced by 1/3. Similarly, for titanium dioxide, we can assume test T2 as a reference case, then in

Test T1, half of the bed mass is considered; in Test T3, the processing time is tripled; in tests T4 to T6, the frequency is doubled; double process time is used in T5 and 4 times the process time in T6.

The resulting granules were classified by coarse sieving using a stack of three sieves of 400 μm , 1 mm and 2 mm aperture size, respectively. For some of the test conditions, the portion of granules bigger than 2 mm was collected to measure the granules' mechanical resistance. For this purpose, a uniaxial compression test was adopted by using an Instron machine (Series 5860) equipped with a 1-N load cell.

3. Results

3.1 Agglomerates' size distribution

Sieve analysis was applied to the processed powders including agglomerates. Significant losses of fines were recorded due to adhesion to the column wall and to elutriation of dust. **Fig. 3a** shows the 2-mm oversize fraction for calcium carbonate. Besides the weight distribution in the different classes identified by the sieving process in **Table 3**, **Fig. 4** also reports an estimate of the median-mass-weighted agglomerate size and the error bars are the diameter range covering the 80 %-by-weight of the distribution of agglomerate size. This latter size range was estimated by fitting the weight distribution by means of a power law. By comparing results, it is possible to observe a limited effect of the operating parameters. In general, the median agglomerate size is between 0.5 and 1.6 mm and the largest agglomerates are above 3–4 mm.

Table 2 Operating conditions in the vibration experiments

Test code	Material	Frequency Hz	Acceleration a/g	Displacement mm	Air rate NL h ⁻¹	Bed mass g	Test time min	Description
C1	CaCO ₃	25	9	6.8	1200	100	10	half time
C2	CaCO ₃	50	9	1.5	1200	100	30	double freq., long time
C3	CaCO₃	25	9	6.8	1200	100	20	reference
C4	CaCO ₃	25	6	4.6	1200	100	20	reduced accel.
T1	TiO ₂	25	9	6.8	1200	100	5	half mass
T2	TiO₂	25	9	6.8	1200	200	5	reference
T3	TiO ₂	25	9	6.8	1200	200	10	double time
T4	TiO ₂	50	9	1.5	1200	200	5	double freq.
T5	TiO ₂	50	9	1.5	1200	200	10	double freq., double time
T6	TiO ₂	50	9	1.5	1200	200	20	double freq., long time



Fig. 3 Examples of agglomerates formed: a) 2-mm oversize fraction for CaCO₃; b) CaCO₃; c) TiO₂.

Table 3 Experimental agglomerate size distributions

Test code	sampled weight fractions in d_a ranges, %			
	< 0.4 mm	0.4–1 mm	1–2 mm	> 2 mm
C1	11.2	22.6	27.6	38.6
C2	43.4	24.4	9.8	22.4
C3	13.6	27.4	21.1	37.9
T1	35.8	19.4	10.5	34.3
T2	26.7	24.8	19.0	29.6
T3	21.2	25.1	18.5	35.2
T4	31.7	23.5	15.3	29.4
T5	29.4	37.5	25.5	35.6
T6	26.5	22.3	22.2	29.0

Increasing the frequency from 25 to 50 Hz has negligible effects on the size of the titanium dioxide agglomerates, while it seems to produce smaller agglomerates of calcium carbonate. Increasing the vibration times results in larger titanium dioxide agglomerates.

3.2 Mechanical resistance of agglomerates

Fig. 5a shows a schematic of the uniaxial compression test carried out on the largest agglomerates with the main geometrical variables of the deformed agglomerate during the test as defined in the following text. An example of the trace of the mechanical response of the agglomerates is reported in **Fig. 6**. The size of the agglomerates, d_a can be determined from the first contact position at which the forces ramp, corresponding to the start of agglomerate

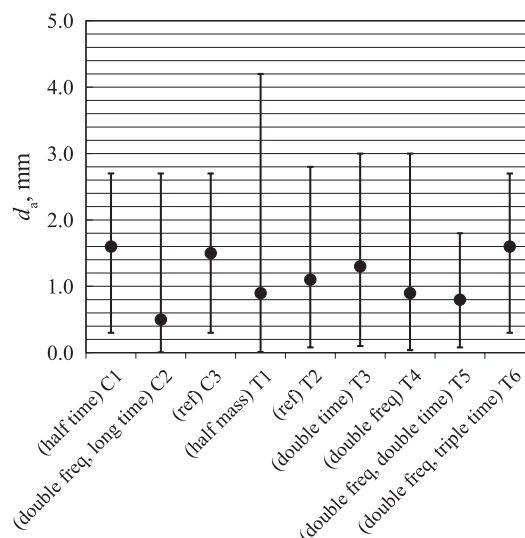


Fig. 4 Agglomerate size distributions for different test conditions obtained from a fitting regression of a power law distribution on the experimental data of **Table 3**. Dots are the median values and bars cover the 80 % range of distributions between the 10th and 90th percentiles.

deformation. The force vs. displacement curve is always well represented by a line segment indicating, as it will be discussed later, a plastic deformation regime of the agglomerate.

The agglomerate rupture is well identified by the peak force. Within the agglomerate deformation regime, the contact deformation, s_c , will be assumed to be half of the agglomerate deformation, s_a , that is the distance travelled by the compression piston starting from the first contact position. Given the contact deformation at breakage, s_{cb} , and the agglomerate deformation at breakage, s_{ab} , it is $s_{cb} = 1/2s_{ab}$, and assuming a spherical agglomerate shape, it is possible to estimate the contact area A_{cb} at breakage

$$A_{cb} = \pi d_a s_{cb} \quad (4)$$

Consequently, the average pressure at the contact at breakage can be easily calculated from the force measured at breakage, F_b :

$$p_b = \frac{F_b}{\pi d_a s_{cb}} \quad (5)$$

The force F_b , the relative deformation of the contact, s_{cb}/d_a , the contact area, A_c , and the pressure p_{fb} measured at breakage in the agglomerate breakage tests are reported as a function of the agglomerate diameter in **Fig. 7** and **Fig. 8** for both calcium carbonate and titanium dioxide, respectively. Data are separated for each of the examined conditions and, correspondingly, a best-fit linear approximation is drawn to highlight possible trends. These figures indicate a clear dependence of both the breakage force (for calcium carbonate only) and also of the contact

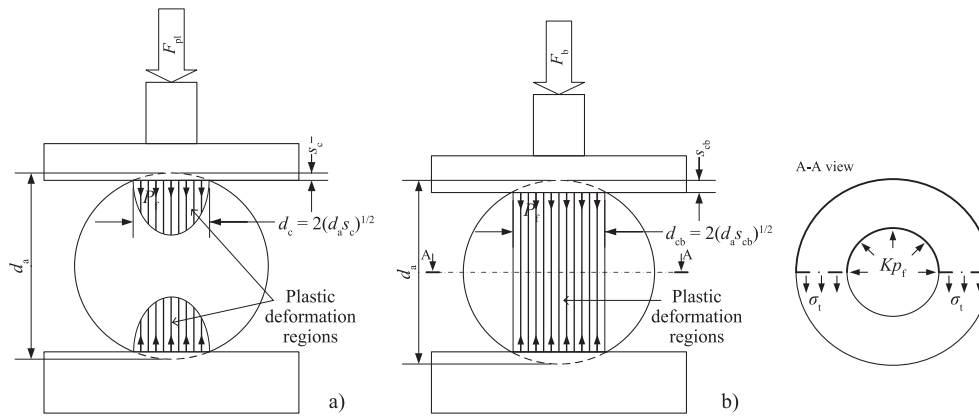


Fig. 5 Uniaxial compression test for agglomerates and contact deformation parameters: a) plastic deformation; b) breakage conditions.

area at breakage on the agglomerate diameter. If any, only a slight dependence on the agglomerate diameter is evident for the relative deformation and the contact pressure at breakage. Furthermore, it is not possible to identify a clear trend of the vibrations and other aggregation process parameters on the observed results. Some differences can be observed comparing two different materials, in fact, with respect to calcium carbonate, the population of agglomerate tested for titanium dioxide is a bit smaller and, in any case, tends to show a slightly higher breakage force (averages around 0.2 N for CaCO_3 and about 0.3 N for TiO_2), a slightly smaller relative deformation at breakage (averages around 0.025 for CaCO_3 and less than 0.020 for TiO_2), correspondingly a slightly lower contact area at breakage (averages around 0.4 mm^2 for CaCO_3 and 0.2 mm^2 for TiO_2) and significantly higher pressures at breakage (averages less than 40 kPa for CaCO_3 and around 100 kPa for TiO_2).

According to Antonyuk S. et al. (2006), a spherical agglomerate compressed against a flat surface will deform and a force will set in between the agglomerate and the surface. This force expression will depend upon the regime of deformation which might be elastic, elastic-plastic or completely plastic. In the presence of an elastic component, the agglomerate deformation will follow a Hertzian law of deformation that reveals an upward concavity in the force-displacement curve. Instead, a purely plastic deformation can be hypothesized in the case of a perfectly linear plastic relationship between the contact deformation and the force. In fact, this is the case in almost all our tests, as is shown in the force vs. displacement curve of **Fig. 6**. The simple Eqn. 6 is used in this case:

$$F_{pl} = \pi p_f d_a s_c \quad (6)$$

where d_a is the agglomerate diameter, s_c is the contact deformation and p_f is the material strength at deformation on the contact point. Eqn. 6 is very simple since it is the

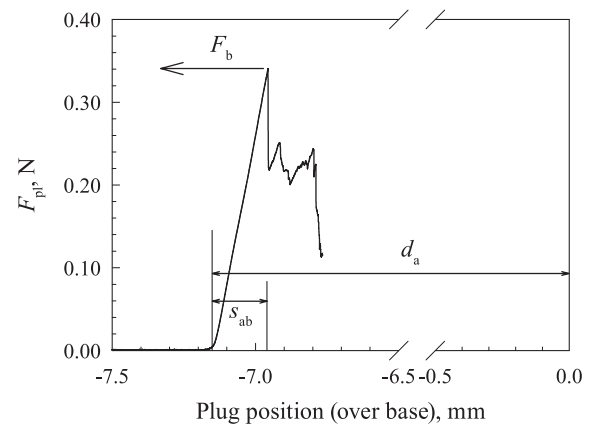


Fig. 6 Force vs displacement curve for agglomerate breakage experiments.

combination of the area of the flattened surface contact point:

$$A_c = \pi d_a s_c \quad (7)$$

and of the pressure exerted by the material p_f .

According to the theoretical works of Hencky H. (1923) and Ishlinsky A.J. (1944) as reported by Molerus O. (1975), p_f can be approximated to three times the material unconfined yield strength. In the present case of agglomerates we have:

$$p_f = 3f_c \quad (8)$$

We assumed that the agglomerate grows by hitting some powder laying on other agglomerates or on the vibrating column surface. Accordingly, the material will consolidate on the agglomerate with subsequent hits in which the consolidation stress σ_1 is equal or smaller than the material strength p_f . The resulting consequence of this assumption and Eqn. 8 is that the flow factor at which the

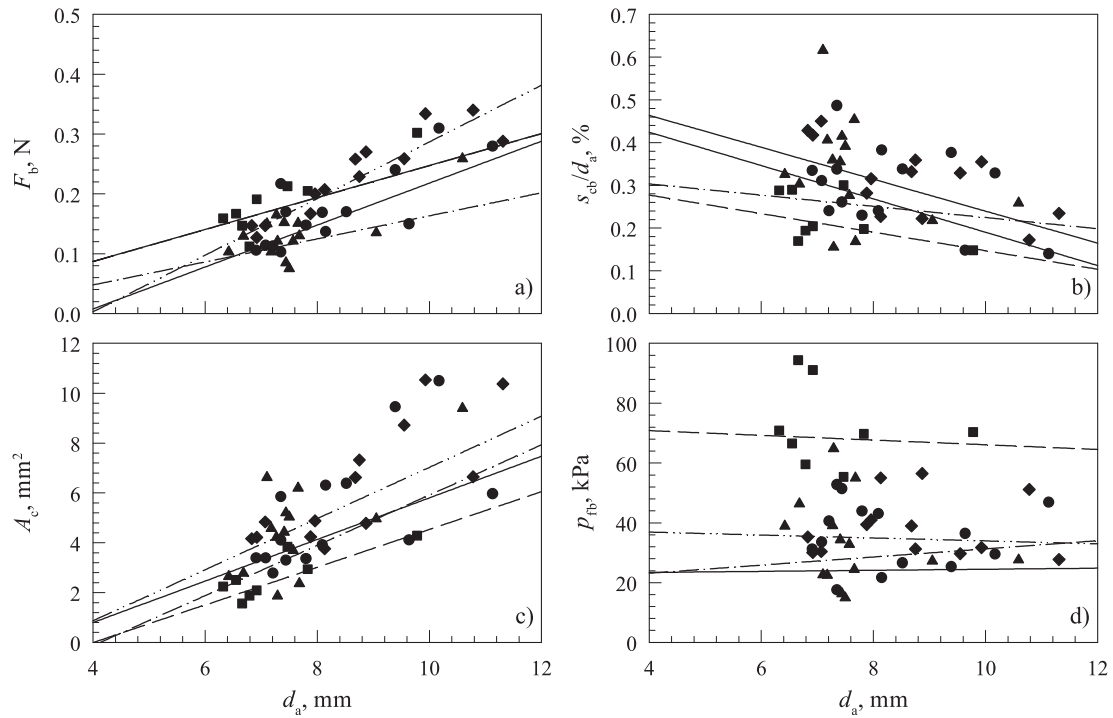


Fig. 7 Force (a), relative deformation of the contact (b), contact area (c) and pressure (d) measured at breakage test for the aggregates as a function of the aggregate diameter for Calcium Carbonate. Test conditions for data points: ●, C1; ■, C2; ▲, C3; ◆, C4. Test conditions for regression lines: —, C1; — —, C2; - - -, C3; - · - ·, C4.

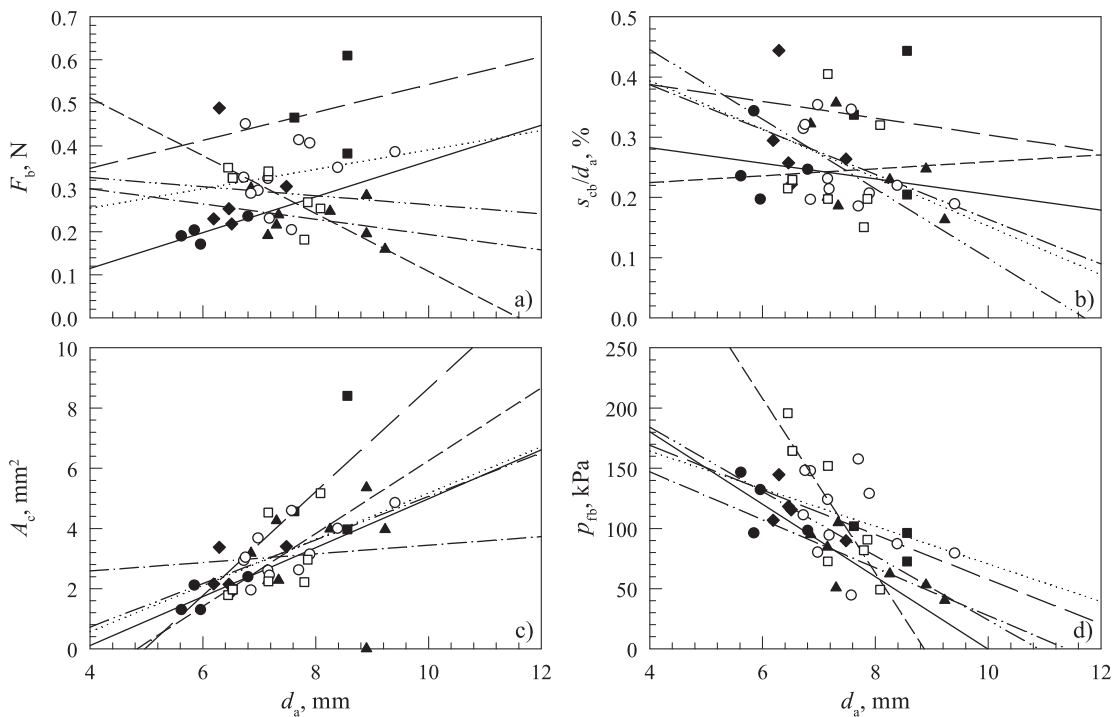


Fig. 8 Force (a), relative deformation of the contact (b), contact area (c) and pressure (d) measured at breakage test for the aggregates as a function of the aggregate diameter for Titanium dioxide. Test conditions for data points: ●, T1; ■, T2; ▲, T3; ◆, T4; ○, T5; □, T6. Test conditions for regression lines: —, T1; — —, T2; - - -, T3; - · - ·, T4; ·····, T5; - · - ·, T6.

material consolidates is:

$$FF = \frac{\sigma_1}{f_c} = \frac{\sigma_1}{p_f} 3 \leq 3 \quad (9)$$

The flow factor line $FF = 3$ is reported in **Fig. 2**. According to the reasoning above, flow functions with flow factors values close to 3, suggest an equilibrium in the agglomerate growth process. Materials with flow functions showing flow factors values smaller than 3 should not be able to produce agglomerated with vibrations. Instead, the agglomeration process by vibration should be largely favored in materials with flow functions characterized by flow factors values larger than 3. This is the case of the tested powders, for which it is verified that both materials have a flow factor smaller than 3. In general, it should be said that according to the mechanism hypothesized to derive Eqn. 9, the agglomerate strength should be largely independent of the vibration parameters and of the agglomerate diameter. This seems to be confirmed by findings in **Fig. 7d**. **Fig. 8d**, instead, may suggest some dependence of the material strength on the agglomerate diameter which, however, should be confirmed by a larger number of samples.

The agglomerate breakage phenomenon has been widely discussed by Antonyuk S. et al. (2005). In particular, it has been highlighted that the agglomerate under plastic deformation breaks because the plasticized nucleus radially expands to the yield of the equatorial band of the particles. **Fig. 3b** shows the mechanism. A rough evaluation of the breakage conditions can be carried out as follows. According to **Fig. 5b**, we assume an inner cylinder of material completely plasticized and characterized by a diameter of $2(d_a s_c)^{0.5}$ and a height of $d_a - 2s_c \approx d_a$. The material in this cylinder pushes radially outwards with a pressure Kp_f , where K is the material vertical to the horizontal stress ratio. Eqn. 2 is valid within the Mohr-Coulomb assumption. The outward pressure of the inner material is balanced by the strength of the material in the unplasticized external toroid. A force balance allows calculation of the collapse condition of this band that occurs when the tangential stress equals the material's unconfined yield strength:

$$p_f K 2\sqrt{d_a s_c} d_a = \sigma_t 2A_t \quad (10)$$

where A_t is the cross-section of the unplasticized toroid. The fact that, in general, it is $s_c \ll d_a$, allows second-order terms to be neglected and therefore:

$$2A_t = \frac{\pi d_a^2}{4} - 2d_a \sqrt{d_a s_c} \quad (11)$$

Furthermore, within the Mohr-Coulomb hypotheses we have:

$$f_c = \frac{2C \cos \phi}{1 - \sin \phi} \quad (12)$$

and

$$\sigma_t = \frac{2C \cos \phi}{1 + \sin \phi} \quad (13)$$

Combining Eqns. 7 and 9 to 12, it is

$$\begin{aligned} & \frac{6C \cos \phi}{1 - \sin \phi} 2K \sqrt{d_a s_c} d_a \\ &= \frac{2C \cos \phi}{1 + \sin \phi} \left(\frac{\pi d_a^2}{4} - 2d_a \sqrt{d_a s_c} \right) \end{aligned} \quad (14)$$

That is

$$\frac{s_c^*}{d_a} = \left\{ \frac{\pi}{8} \left/ \left[\left(\frac{1 + \sin \phi}{1 - \sin \phi} \right) 3K - 1 \right] \right. \right\}^2 \quad (15)$$

It appears that the agglomerate deformation at breakage expressed by Eqn. 14 should be a function only of the material properties. The values predicted for the deformation at breakage for the two materials are reported in **Table 2**. It can be verified that also the theory predicts a result that is independent of the vibration parameters and of the agglomerate diameter as roughly suggested by **Figs. 7b** and **8b**. Furthermore, in agreement with the experiments, the theory predicts a smaller deformation at breakage for titanium dioxide than for calcium carbonate.

4. Conclusion

The process of agglomerate formation by means of mechanical vibrations was studied by means of agglomerate size distributions and uniaxial compression tests on agglomerate deformation and resistance. Results indicate the formation of wide agglomerates' size distributions and hard and compact agglomerates.

Considering the experimental results and the interpretation of data, it is suggested that in order to produce agglomerates with this mechanism, powders should have flow functions close or smaller than a flow factor value of 3. The same analysis suggests that agglomerates' consolidation pressures and deformation at breakage is almost independent of the agglomerate diameter and of the vibration conditions.

Nomenclature

a	acceleration due to vibration (m s^{-2})
A	vibration amplitude (m)
A_c	contact area (mm^2)

A_{cb}	contact area at breakage (mm^2)
A_t	cross-section of the unplasticized toroid (mm^2)
D	mold diameter (mm)
d_a	agglomerate diameter (mm)
d_p	particle diameter (μm)
f	oscillation frequency (s^{-1})
F_b	force measured at breakage (N)
F_{pl}	force measured in the agglomerate plastic deformation range (N)
f_c	unconfined yield strength (Pa)
FF	flow factor (–)
g	acceleration due to gravity (m s^{-2})
ID	internal diameter (mm)
K	vertical to horizontal stress ratio (–)
p_b	average pressure at the contact at agglomerate breakage (kPa)
p_f	the material strength at the agglomerate contact point (kPa)
p_{fb}	pressure measured at breakage at the agglomerate contact point (kPa)
s_a	agglomerate deformation (mm)
s_{ab}	agglomerate deformation at breakage (mm)
s_c	contact deformation (mm)
s_{cb}	contact deformation at breakage (mm)
Z	final sample height after consolidation (mm)
ρ_b	average bed density (kg m^{-3})
ρ_p	particle density (kg m^{-3})
σ	normal stress (Pa)
σ_0	applied normal stress on the sample surface in the uniaxial tester (Pa)
σ_1	major principal stress at consolidation (Pa)
σ_t	tensile strength, Pa
ϕ	angle of internal friction (Deg)
ϕ_e	effective angle of internal friction (Deg)
ϕ_w	angle of wall friction (Deg)
μ_w	mold wall friction (–)
ω	vibration pulsation (s^{-1})

References

- Antonyuk S., Tomas J., Heinrich S., Mörl L., Breakage behaviour of spherical granulates by compression, *Chemical Engineering Science*, 60 (2005) 4031–4044, DOI: 10.1016/j.ces.2005.02.038.
- Antonyuk S., Khanal M., Tomas J., Heinrich S., Mörl L., Impact breakage of spherical granules: experimental study and DEM simulation, *Chemical Engineering and Processing: Process Intensification*, 45 (2006) 838–856, DOI: 10.1016/j.cep.2005.12.005.
- Barletta D., Donsi G., Ferrari G., Poletto M., Russo P., Solid flow rate prediction in silo discharge of aerated cohesive powders, *AIChE Journal*, 53 (2007) 2240–2253, DOI:10.1002/aic.11212.
- Barletta D., Poletto M., Aggregation phenomena in fluidization of cohesive powders assisted by mechanical vibrations, *Powder Technology*, 225 (2012) 93–100, DOI: 10.1016/j.powtec.2012.03.038.
- Barletta D., Poletto M., A device for the measurement of the horizontal to vertical stress ratio in powders, *Granular Matter*, 15 (2013) 487–497, DOI: 10.1007/s10035-013-0427-7.
- Barletta D., Russo P., Poletto M. Dynamic response of a vibrated fluidized bed of fine and cohesive powders, *Powder Technology*, 237 (2013) 276–285, DOI: /10.1016/j.powtec.2012.12.004
- Cruz M.A.A., Passos M.L., Ferreira W.R., Final drying of whole milk powder in vibrated-fluidized beds, *Drying technology*, 23 (2005) 2021–2037, DOI: 10.1080/07373930500210473.
- Janssen H.A., Versuche über Getreidedruck in Silozellen, *Zeitschrift des Vereins Deutscher Ingenieure*, 39 (1895) 1045–1049.
- Kua N., Hare C., Ghadiri M., Murtagh M., Oram P., Haber R., Auto-granulation of fine cohesive powder by mechanical vibration, *Procedia Engineering*, 102 (2015) 72–80, DOI: 10.1016/j.proeng.2015.01.108.
- Kwade A., Schulze D., Shweddes J. Determination of the Stress Ratio in Uniaxial Compression Tests—Part2, *Powder Handling and Processing*, 6 (1994) 199–203.
- Hencky H., Über Einige Statisch Bestimmte Fälle Des Gleichgewichts In Plastischen Körpern, *Zeitschrift für Angewandte Mathematik und Mechanik*, 3 (1923) 241–251, DOI: 10.1002/zamm.19230030401.
- Ishlinsky A.J., The axi-symmetrical problem in plasticity and Brinell test, *Journal of Applied Mathematics and Mechanics (USSR)*, 8 (1944) 201–224.
- Mawatari Y., Tatemoto Y., Noda K., Yamamura M., Kageyy H., Vibro-fluidization characteristics for size arranged agglomerates, *Proc. of The 12th Int. Conf. on Fluidization—New Horizons in Fluidization Engineering Vancouver, Canada*, May 13–18, (2007) 424–432.
- Molerus O., Theory of yield of cohesive powders, *Powder Technology*, 12 (1975) 259–275, DOI: 10.1016/0032-5910(75)85025-X.
- Schulze D., Development and application of a novel ring shear tester, *Aufbereitungstechnik*, 35 (1994) 524–535.
- Parrella L., Barletta D., Boerefijn R., Poletto M., Comparison of uniaxial compaction tester and shear tester for characterization of powder flowability, *Kona Journal*, 26 (2008) 178–189, DOI: 10.14356/kona.2008016.
- Van Ommen J.R., Valverde J.M., Pfeffer R., Fluidization of nanopowders: a review, *Journal of Nanoparticle Research*, 14 (2012) 1–29, DOI: 10.1007/s11051-012-0737-4.

Author's short biography



Hamid Salehi Kahrizsangi

Hamid Salehi Kahrizsangi is a PhD student at the Department of Industrial Engineering, University of Salerno, Italy. He graduated from Lund University, Lund, Sweden, as a food engineer specialized in powder technology in 2012.



Diego Barletta

Diego Barletta is assistant professor of chemical engineering at the Faculty of Engineering of the University of Salerno. His research interests include powder flow from storage units, rheology of powders and biomass particulate solids, fluidization of cohesive powders assisted by vibrations and process systems engineering for renewable energy. He is the author of more 30 papers on refereed international journals and books on chemical engineering and of more than 50 papers for international conferences. He reviews papers for international journals and conferences on chemical engineering and powder technology.



Massimo Poletto

Massimo Poletto is professor of chemical engineering since December 2012 at the Department of Industrial Engineering. Since January 2011, he has served as the chairman of the degree programme board of chemical and food engineering. In the period 2008–2013, he served as the chairman of a working party of the European Federation of Chemical Engineering (EFCE) on “Mechanics of Particulate Solids” that he joined in 2004 as a delegate from the Italian Association of Chemical Engineering (AIDIC). He is a member of the editorial board of Chemical Engineering Research and Design, the official journal of IChemE and of EFCE. (ChERD, www.icheme.org/journals).